Statistical mechanical models and tensor network decoding for quantum codes

Christopher T. Chubb ETH Zürich

Stat mech mapping (with Steve Flammia, AWS) arXiv:2101.04125, to appear in AIHP:D

2D tensor network decoding arXiv:2101.04125

Tensor contraction Julia package Coming soon!

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More generally, two important questions arise for any quantum code:

- How do I decode?
- What is the threshold?

The statistical mechanical mapping¹ allows us to systematically address both questions for codes subject to stochastic Pauli noise.

It achieves this by mapping the answers onto the phase boundary of a disordered classical stat mech model.

¹Dennis, Kitaev, Landahl, Preskill, JMP 2002, doi:10/cs2mtf, arXiv:quant-ph/0110143

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Introduction	& Pauli noise		mechanical model	
Independent case	Threshold	\longleftrightarrow	Phase transition	
EC as a phase transition	Threshold			
Correlated case	Deceding		Calculating partition functions	
Tensor network decoding	Decoding	\longleftrightarrow		
Codes studied				
Results	Allows us to reappropriate techniques for studying stat mech systems to study quantum			
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	Threshold approximation	\leftarrow	Monte Carlo simulation	
	Optimal decoding	<i>~</i>	Partition function calculation	

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Stat mech mapping:

- Generalise the mapping to correlated noise for arbitrary subsystem codes
- Numerically study the toric code with mildly correlated errors
- Show how circuit noise can be studied, allowing for fault-tolerant thresholds to be approximated
- Generalise the tensor network decoder of Bravyi, Suchara and Vargo

Tensor network decoding:

- Develop a linearithmic contraction algorithm for 2D tensor networks
- Apply this to several surface/colour codes, including irregular codes
- Provide evidence for a conjecture about surface code thresholds

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Independent case: Hamiltonian

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Let $\llbracket A, B \rrbracket$ be the scalar commutator of two Paulis, such that $AB =: \llbracket A, B \rrbracket BA$.

For a stabiliser code generated by $\{S_k\}_k$, and an error Pauli *E*, the (disordered) Hamiltonian *H_E* is defined

$$H_{E}(\vec{s}) := -\sum_{i} \sum_{\sigma \in \mathcal{P}_{i}} \underbrace{J_{i}(\sigma)}_{\mathcal{J}(\sigma)} \underbrace{\mathbb{I}[\sigma, E]}_{k: \llbracket \sigma, S_{k} \rrbracket = -1} \underbrace{\mathsf{DoF}}_{k: \llbracket \sigma, S_{k} \rrbracket = -1}$$

for $s_k = \pm 1$, and coupling strengths $J_i(\sigma) \in \mathbb{R}$.

Take-aways:

- ullet lsing-type, with interactions corresponding to single-site Paulis σ
- Disorder *E* flips some interactions (Ferro \leftrightarrow Anti-ferro)
- \bullet Local code \implies local stat mech model

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$$H_{E}(\vec{s}) = -\sum_{i} \sum_{\sigma \in \mathcal{P}_{i}} J_{i}(\sigma) \llbracket \sigma, E \rrbracket \prod_{k : \llbracket \sigma, S_{k} \rrbracket = -1} s_{k}$$

Jsing $\llbracket A, B
rbracket \llbracket A, C
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rbracket$, we see this system has a gauge symmetry

 $s_k \rightarrow -s_k$ and $E \rightarrow ES_k$.

This gauge symmetry will capture the logical equivalence of errors, $Z_E = Z_{ES_k}$.

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Suppose we have an independent error model

$$\Pr(E) = \prod_i p_i(E_i),$$

we now want $Z_E = \Pr(\overline{E})$, \overline{E} is the error class

 $\overline{E}:=\{ES|S\in \mathcal{S}\}$.

Using the gauge symmetry we have that the partition function can be written as a sum stabiliser-equivalent errors

$$Z_E = \sum_{\vec{s}} e^{-\beta H_E(\vec{s})} = \sum_{S} e^{-\beta H_{ES}(\vec{1})} = \sum_{F \in \overline{E}} e^{-\beta H_F(\vec{1})}$$

If we select the coupling strength such that $e^{-\beta H_E(\bar{1})} = \Pr(E)$, then $Z_E = \Pr(\overline{E})$ will follow.

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We now want to pick our couplings such that $e^{-\beta H_E(\vec{1})} = \Pr(E)$. Expanding this out, we get

$$\sum_{i} \log p_i(E) = -\sum_{i} \sum_{\sigma} \beta J_i(\sigma) \llbracket \sigma, E \rrbracket.$$

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Nishimori condition: $\beta J_i(\sigma) = \frac{1}{4} \sum_{\tau \in \mathcal{P}} \log p_i(\tau) \llbracket \sigma, \tau \rrbracket,$

which implies $e^{-eta H_{E}(ec{\mathbf{I}})} = \Pr(E)$, and therefore $Z_{E} = \Pr(\overline{E})$.

This intrinsically links the error correcting behavior of the code to the thermodynamic behavior of the model (along the Nishimori line).

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Toric code with iid bit-flips

ep 1: Degrees of freedom

 $s_v = \pm 1$ on each vertex v

Step 2: Interactions

$$H_I = -\sum_{v \sim v'} J \, s_v s_{v'}$$

$$\begin{split} H_E &= -\sum_{v \sim v'} J e_{vv'} \, s_v s_{v'} \\ \text{where } e_{vv'} &= \begin{cases} +1 & E_{vv'} = I, \\ -1 & E_{vv'} = X. \end{cases} \end{split}$$

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Toric code and the random-bond Ising model

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Step 3: Disorder

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 $\pm J$ Random-bond Ising Model

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Toric code

$\mathsf{Bit-flip} \to \mathsf{Random-bond}\ \mathsf{lsing}^1$

Indep. $X\&Z \rightarrow 2 \times \text{Random-bond Ising}$ Depolarising \rightarrow Random 8-vertex model²

Colour code

Bit-flip \rightarrow Random 3-spin Ising Indep. $X\&Z \rightarrow 2\times$ Random 3-spin Ising Depolarising \rightarrow Random interacting 8-vertex²







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Toric code

Bit-flip \rightarrow Random-bond Ising¹ Indep. $X\&Z \rightarrow 2 \times$ Random-bond Ising Depolarising \rightarrow Random 8-vertex model²



Colour code

Bit-flip \rightarrow Random 3-spin Ising Indep. $X\&Z \rightarrow 2 \times$ Random 3-spin Ising Depolarising \rightarrow Random interacting 8-vertex²



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Colour code





Error correction threshold as a quenched phase transition

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Consider the free energy cost of a logical error L,

$$\Delta_E(L) = -rac{1}{eta} \log Z_{EL} + rac{1}{eta} \log Z_E.$$

Along the Nishimori line

$$\Delta_E(L) = \frac{1}{\beta} \log \frac{\Pr(\overline{E})}{\Pr(\overline{EL})},$$

which implies

ow threshold : $\Delta_E(L) o \infty$ (in me ove threshold : $\Delta_E(L) o 0$ (in pro-

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Phase diagram sketch



Noise parameter

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The key point independence gave us was the ability to factor our noise model

$$\Pr(E) = \prod_i p_i(E_i).$$

We can generalise this to correlated models:

Factored distribution

An error model factors over regions $\{R_j\}_j$ if there exist $\phi_j:\mathcal{P}_{R_j} o\mathbb{R}$ such that

$$\Pr(E) = \prod_{j} \phi_j(E_{R_j})$$

This model includes many probabilistic graphical models, such as Bayesian Networks and Markov/Gibbs Random Fields.

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By construction, we can extend to the correlated case by changing $\sigma \in \mathcal{P}_i$ to $\sigma \in \mathcal{P}_{R_i}$:

 $H_{\mathsf{E}}(\vec{s}) := -\sum_{j} \sum_{\sigma \in \mathcal{P}_{\mathsf{R}_{j}}} J_{j}(\sigma) \llbracket \sigma, \mathsf{E} \rrbracket \prod_{k : \llbracket \sigma, \mathsf{S}_{k} \rrbracket = -1} \mathsf{s}_{k}$

 $eta J_j(\sigma) = rac{1}{|\mathcal{P}_{\mathcal{R}_j}|} \sum_{ au \in \mathcal{P}_{\mathcal{R}_i}} \log \phi_j(au) \left[\!\!\left[\sigma, au
ight]\!
ight],$

As before we get that $Z_E = \Pr(\overline{E})$, and so the threshold manifests as a phase transition.

Nishimori condition:

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'Across plaquette' correlated bit-flips



Model specified by

 $\begin{array}{ll} \Pr(I_e|I_{e'}) & \Pr(I_e|X_{e'}) \\ \Pr(X_e|I_{e'}) & \Pr(X_e|X_{e'}) \end{array}$

for all neighbouring edges e and e'.

Convenient parameterisation:

$$p := \Pr(X_e), \quad \eta := \frac{\Pr(X_e|X_{e'})}{\Pr(X_e|I_{e'})}.$$

'Across plaquette' correlated bit-flips



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Monte Carlo simulations



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Can the stat mech model give us a decoder?

If an error E occurs, a decoder needs to select one of the degenerate logical error classes

$$\overline{E}$$
 $\overline{EL_1}$ $\overline{EL_2}$ $\overline{EL_3}$...

The optimal (maximum likelihood) decoder selects the most likely class

$$D_{ML} = \overline{EL_l}$$
 where $l = \arg \max_l \Pr(\overline{EL_l})$.

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Decoding from partition functions

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Along the Nishimori line, the maximum likelihood condition corresponds to maximising the partition function

$$I = \operatorname*{arg\,max}_{I} Z_{EL_{I}}.$$

Approximating Z_{EL_1} therefore allows us to approximate the ML decoder.

- Step 1: Measure the syndrome *s*
- Step 2: Construct an arbitrary error C_s which has syndrome s
- Step 3: Approximate $Z_{C_sL_l} = Pr(\overline{C_sL_l})$ for each logical l
- Step 4: Find the *I* such that $Z_{C_sL_l}$ is maximised
- Step 5: Apply $(C_s L_l)^{-1}$

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ML decoding as a tensor network



- Partition functions, and thus error class probabilities, can be expressed as tensor networks^{2,3}.
- There is a tensor for each qubit, and for each stabiliser
- By approximating these class probabilities we can find the ML error

 ²Verstraete et. al., PRL 2006, doi:10/dfgcz8, arXiv:quant-ph/0601075
 ³Bridgeman and Chubb, JPA 2017, doi:10/cv7m, arXiv:1603.03039

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Tensor network decoding

- We sweep along the network, using lossy compression of Matrix Product States
- To do this for general graphs we need to use a sweepline approach



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Surface codes on different lattices



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How does the surface code perform on different lattices/graphs?

aise or lower the connectivity





Irregular graphs





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Non-SC topological models

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We also want to capture 2D models that aren't (ostensibly) surface codes.

Colour code



Subsystem surface code



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Thresholds

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	Bit-flip		Phase-flip		Depolarising	
	Observed	Upper bound	Observed	Upper bound	Observed	Upper bound
Surface code (reg.)						
Square	10.917(5)%	10.9187%	10.917(5)%	10.9187%	18.81(3)%	18.9(3)%
Tri./Hex.	16.341(7)%	16.4015%	6.748(5)%	6.7407%	13.81(7)%	?
Kag./Rho.	9.875(5)%	?	11.910(6)%	?	18.09(4)%	?
T.H./Asa.	4.297(7)%	?	20.701(13)%	?	9.07(8)%	?
Surace code (irr.)						
Rand. Tri.	17.128(15)%	?	6.237(9)%	?	12.85(3)%	?
Rand. Quad.	12.195(12)%	?	9.715(11)%	?	18.05(3)%	?
Subsystem SC						
Square	6.705(13)%	6.7407%	6.705(13)%	6.7407%	11.23(3)%	?
Colour Code						
Hexagonal	10.910(5)%	10.9(2)%	10.910(5)%	10.9(2)%	18.68(2)%	18.9(3)%

Surface code saturating the Hashing Bound

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We find a trade-off between the X and Z thresholds.

Thresholds saturate the hashing bound

 $h(\tau_x) + h(\tau_z) \le 1$

Pair matching studied earlier by Fujii et.al.⁴



⁴Fujii et.al., doi.org/d5sb, arXiv:1202.2743

Surface code saturating the Hashing Bound

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Pair matching studied earlier by Fujii et.al.⁴

	Entropy		
	MWPM ¹	TN	
Regular			
Square	0.957	0.9948(3)	
Tri./Hex.	0.979	0.9989(3)	
Kag./Rho.	0.971	0.9918(3)	
T.H./Asa.	0.979	0.9915(6)	
Irregular			
Rand. Tri.	?	0.9974(7)	
Rand. Quad.	?	0.9948(7)	

⁴Fujii et.al., doi.org/d5sb, arXiv:1202.2743

Future work

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- Stat mech mapping beyond Pauli codes
- Using the stat mech mapping for more than the threshold
- TN decoding of correlated noise
- TN decoding in 3D (including noisy 2D) and beyond, LDPCs, etc.

Thank you!

Stat mech mapping: arXiv:1809.10704, to appear in AIHPD Tensor network decoding: arXiv:2101.04125 Tensor contracting package: Coming soon!

- me@christopherchubb.com
 - ${}^{lacksymbol{\otimes}}$ christopherchubb.com
 - 9 @QuantumChubb